

# PLANNING, DESIGN, and REALIZATION OF AUTOMATED TERMINALS

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moffatt & nichol

Creative People, Practical Solutions.®

# Moffatt & Nichol

- Founded in 1945 in Southern California to serve the U.S. Navy & the evolving port & maritime industries
- 600+ employees w/29 offices (North America, Europe, Latin America, Middle East, Pacific Rim)
- A recognized leader in marine terminal planning, analysis, design & goods movement economics



# Services for Development of Automated Terminal Matrix

Services	Moffatt & Nichol	Typical Simulation Consultant	Typical Infrastructure Consultant	Typical Equipment Vendor
Master Planning	✓	✓	✓	
Investment Advisory	✓			
Basis of Design	✓		✓	
Simulation	✓	✓		✓
Interface Plan	✓			
Equipment Specifications	✓			✓
IT, Application Specifications	✓			
Design (infrastructure)	✓		✓	
Procurement Process:				
Equipment	✓			✓
IT, Application	✓			
Program Management (infrastructure)	✓		✓	
Contract Management (equipment)	✓			
Emulation	✓	✓		
Training	✓			
Go-Live Support	✓			
Optimization	✓			

# The Business Case

**E<sup>3</sup>**

**Economical**

(meeting the business case)

**Efficient**

(delivering capacity, speed and reliability at lowest cost)

**Environmentally sustainable**

(lowest energy consumption)

# Planning and Layout – Tailoring to Fit the BC

- So, the planner is like a tailor
- He must try to fashion the terminal to fit the business case perfectly

## CAPACITY

- Annual throughput

## PRODUCTIVITY

- Vessel
- Gate
- Rail

## COST

- Facilities
- Equipment
- Labor
- Energy



- **One size does not fit all!**

# Conventional “Bottom-Up” Planning



Operations

Logistics

Equipment

Infrastructure

**Traditional**



# New “Top-Down” Planning

New

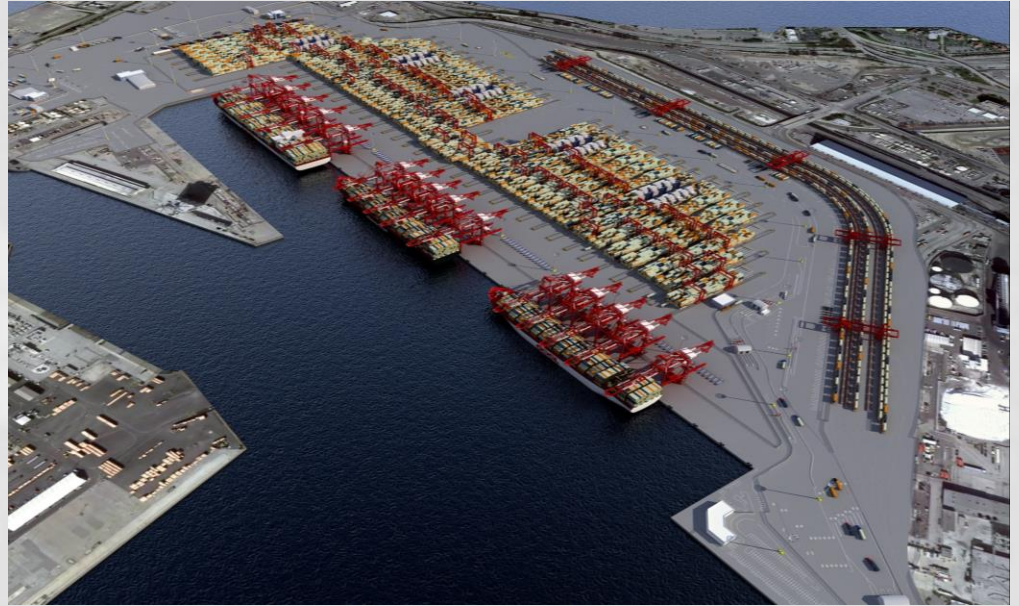


Operations

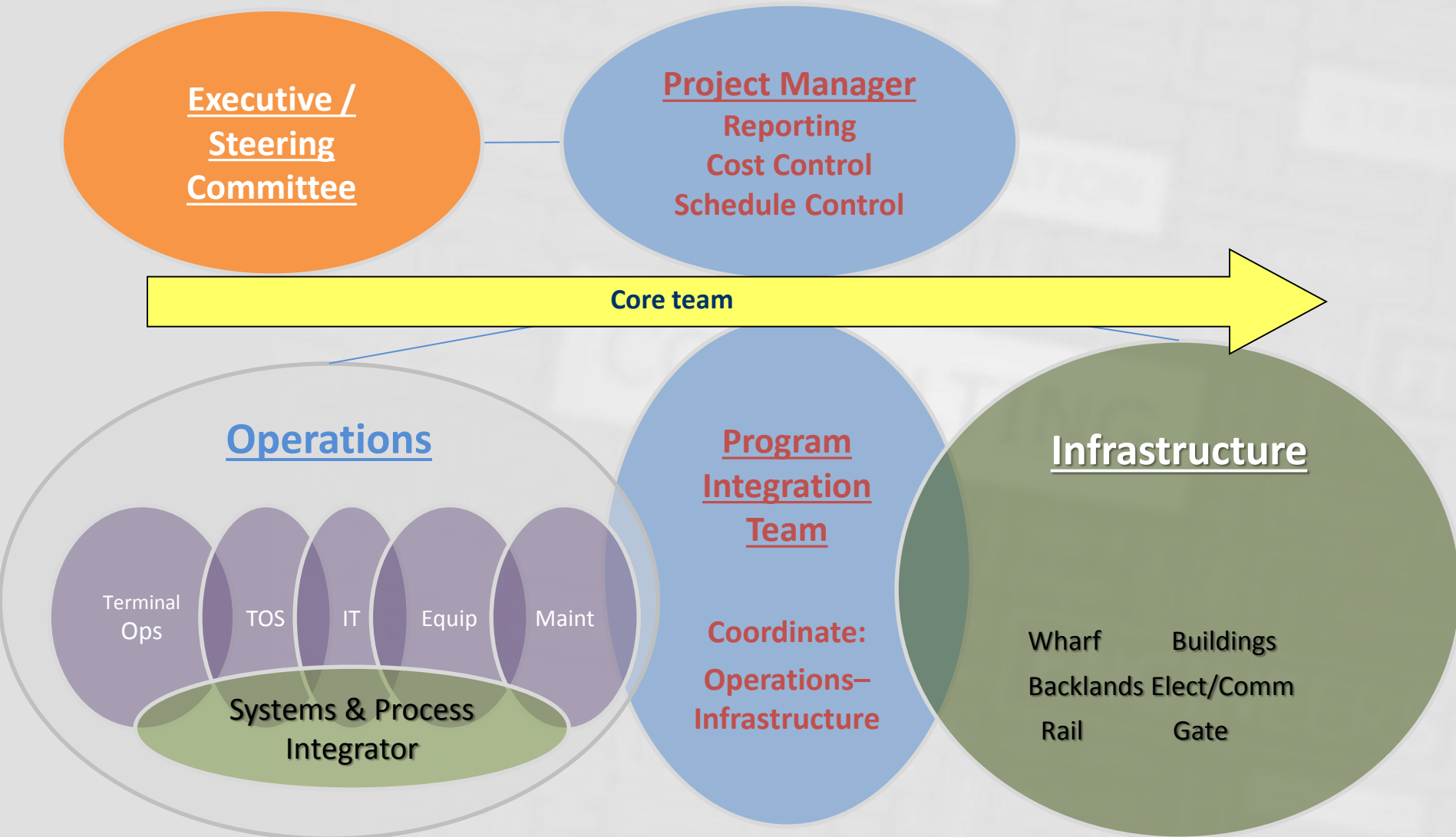
Logistics

Equipment

Infrastructure



# Project Organization?

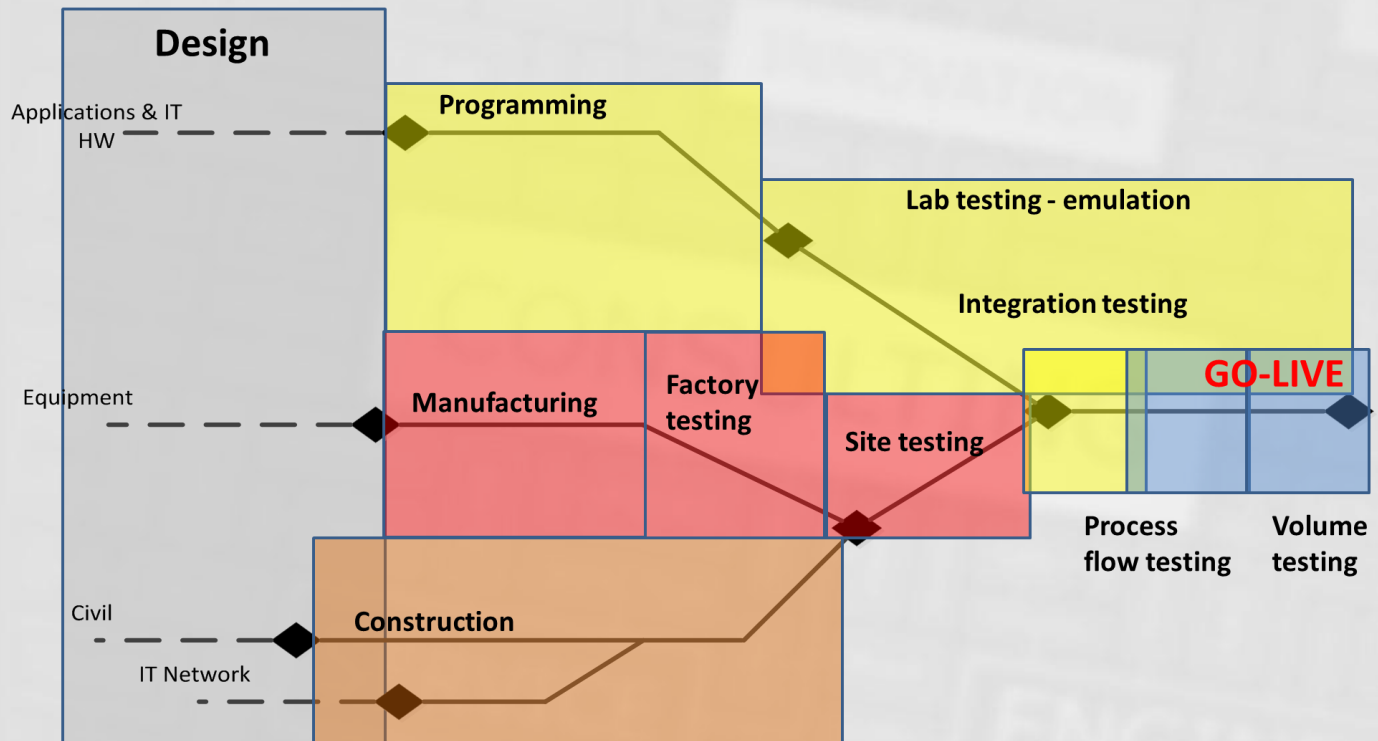




# Development Philosophy

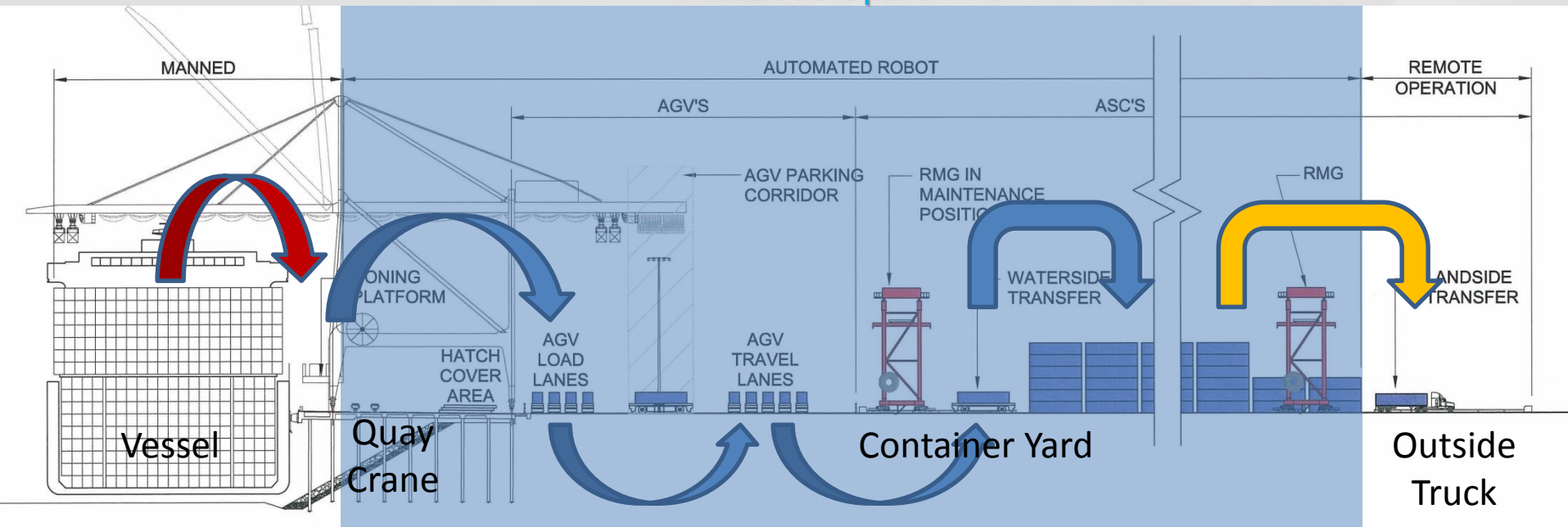
- The infrastructure for an automated terminal is fixed for its economic life
- An automated container terminal will be designed to perform under high utilization
- It is critical to predict performance and operating cost for the life of the infrastructure
- An early preparation of well-integrated, long-term masterplan and development plan is required

# Path to Completion is Complex



# Wharf

## Robotic Operation



Manned  
Main Trolley

Automated  
Secondary  
Trolley

Automated  
Horizontal  
Transport  
AGV's

Automated  
Container  
Stacking,  
Retrieval,  
Shuffling  
ASC's

Semi-  
Automated  
Delivery to  
Outside  
Truck

# Wharf Design Issues



# Wharf Design Issue

- Quay design load will depend on crane:
  - Gage
  - Back reach
  - Out reach
  - Setback from face of the quay
  - Type of operation (tandem, single, double trolley etc.)
  - Wind and seismic load
  - Crane wharf interaction





# Seismic Design Approach

- Performance-based design approach:
  - Operating Level Earthquake (OLE)
  - Contingency Level Earthquake (CLE)
  - Code-Level Design Earthquake (DE)
- Performance goals:
  - OLE performance = No damage
  - CLE performance = Repairable damage
  - DE performance = No collapse



# Berthing and Mooring Loads

- Berthing Load

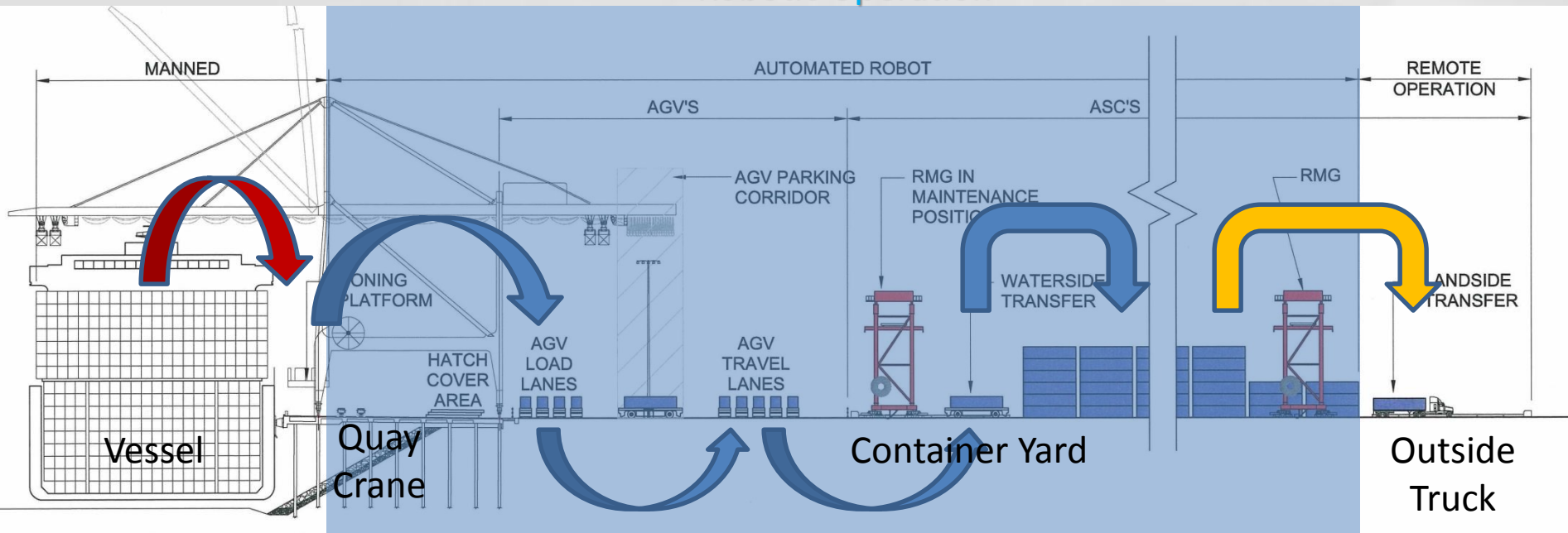
- Design Vessel 20,000 TEU +
- Ship Approach Velocity and Angle 0.26 ft/s , 5°
- Length Overall (LOA) 1,300 feet +
- Maximum Displacement 254,000 metric tons +
- Beam 194 feet
- Maximum Draft 50.8 feet
- Allowable Hull Pressure 4.13 ksf

- Mooring Load

- 200 metric ton bollards

# Horizontal Transport Area

## Robotic Operation



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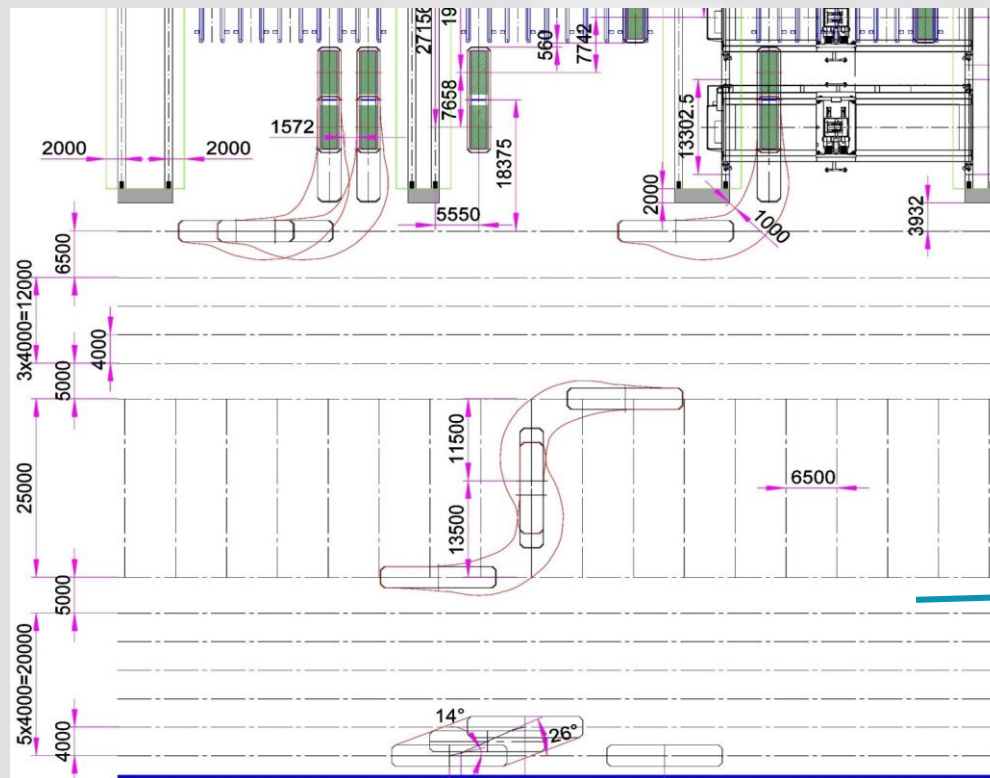
# Horizontal Transport

- Gathering and distributing tasks to/from storage
  - Move any box, from any location to any location at any time
- Must be rubber-tired
  - AGV/L-AGV (diesel/ battery operated)
  - AShC/AStraddle (hybrid diesel)



# Typical AGV Traffic Layout

- It is important to understand the traffic pattern
- Operationally acceptable grades
- Requirements for systems such as transponders and magnets
- Appropriate position for all above ground structures



6 long travel lanes

Cross-travel  
and holding lanes

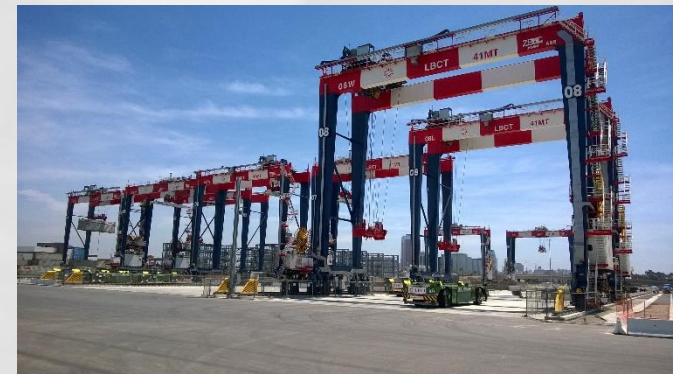
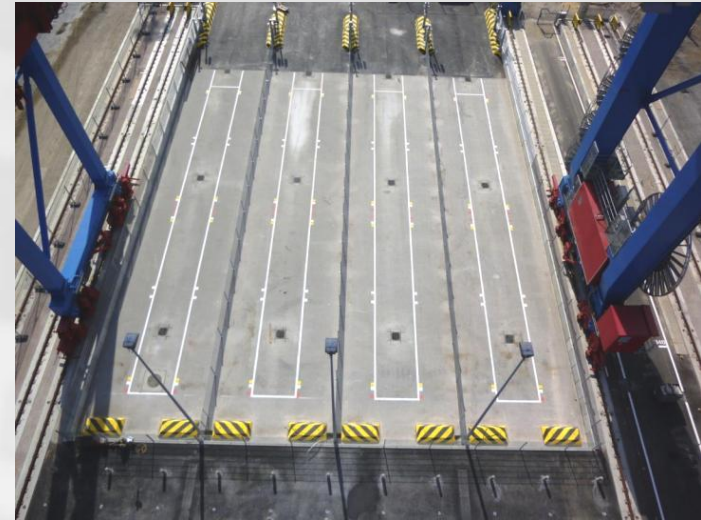
1 long travel lane

6 transfer lanes

LS QC rail

# WS Transfer Area

- Understand the operational requirements
- Interface with AGV system
- Interface with ASC control/ safety systems
- Load repetition
- Durability of pavement
- Different solutions for different modes of operation





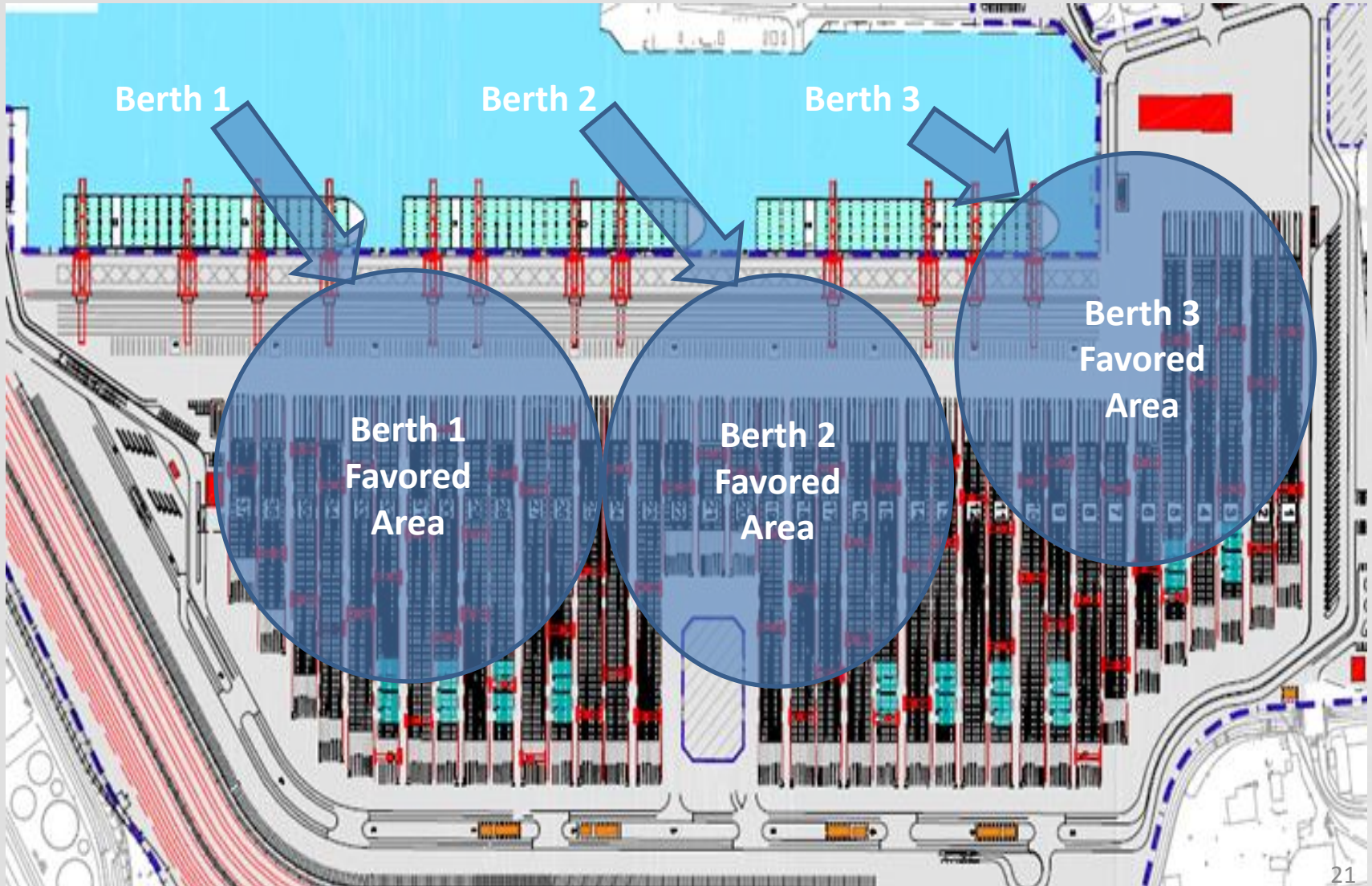
# Pavement Areas





# Vehicle / Wheel Load Repetition

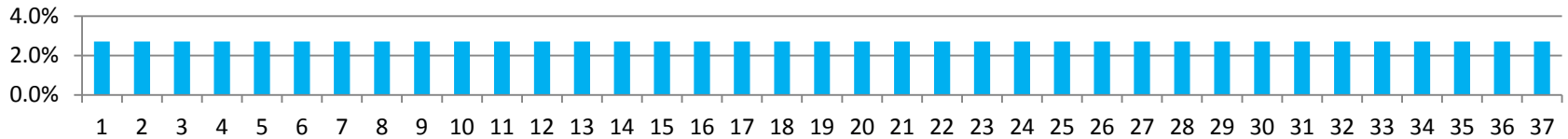
## *Favored Storage Location*



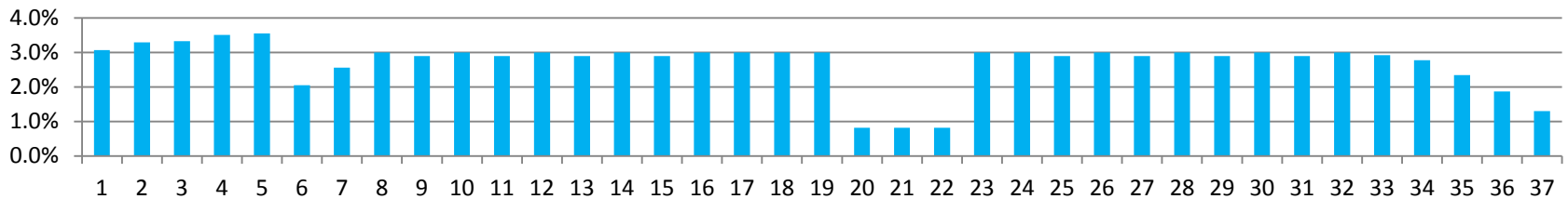
# Vehicle / Wheel Load Repetition

## *Container Location Distribution*

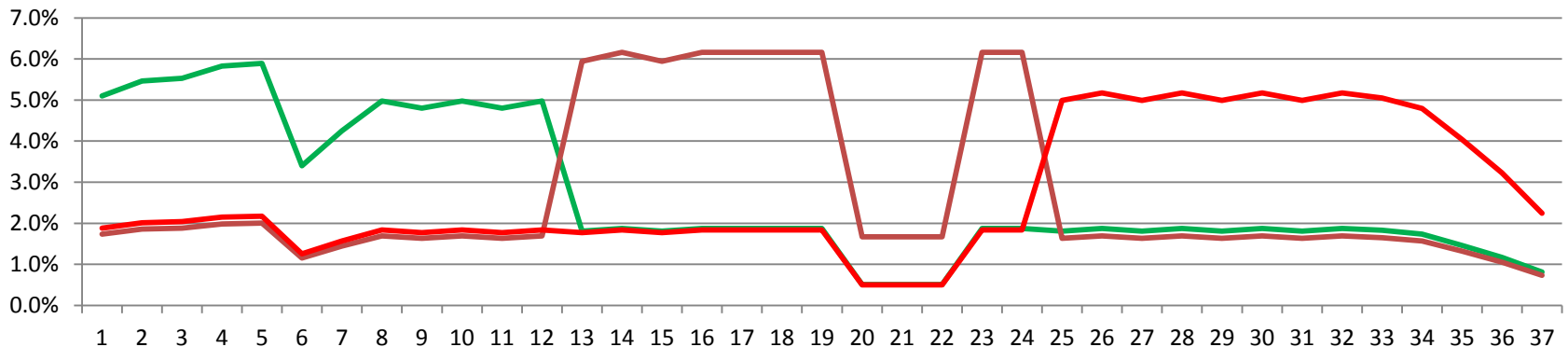
### Equal Storage



### Proportional Storage



### 60% to Favored Storage



Block Index

Berth Location 8 - 20

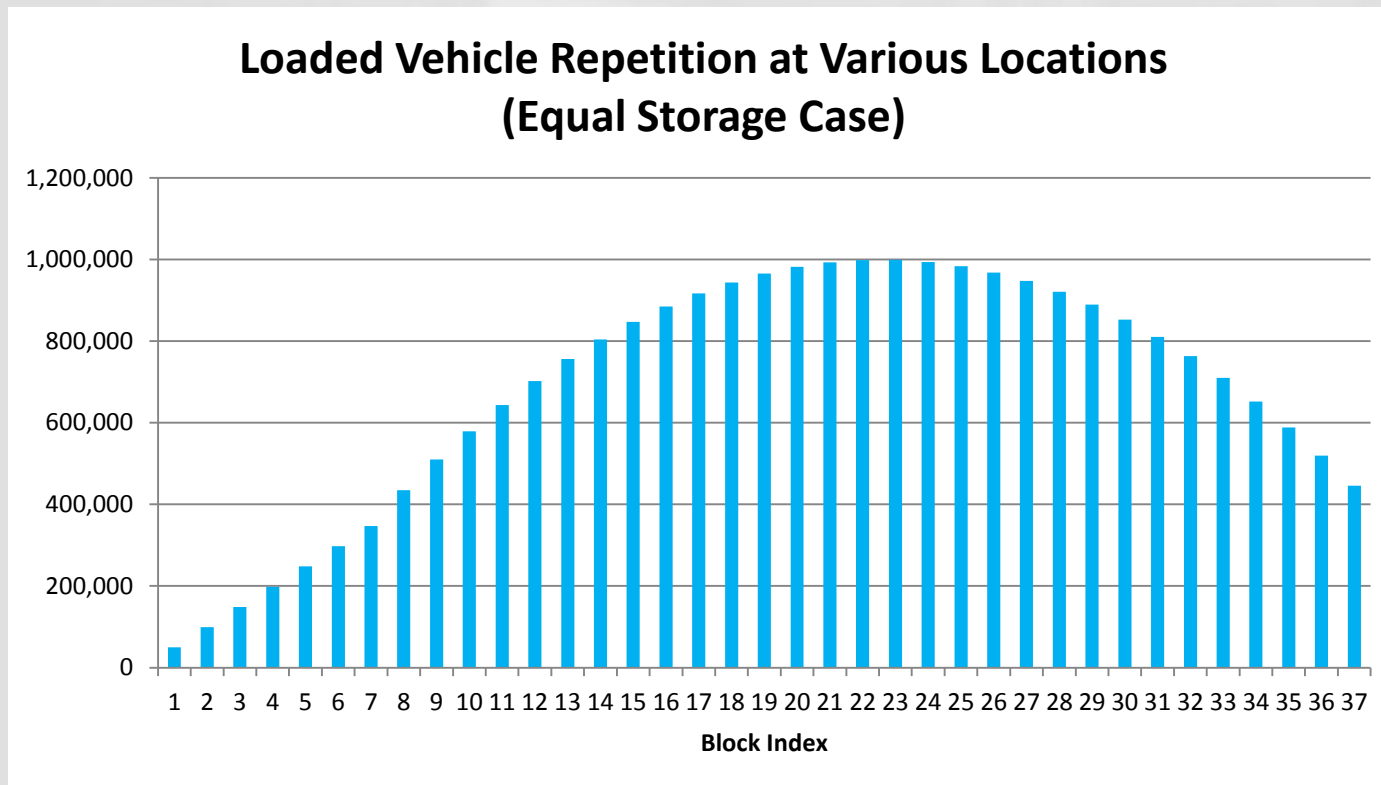
Berth Location 21 - 31

Berth Location 32 - >37

# Vehicle / Wheel Repetition

## *Results – Equal Storage Case*

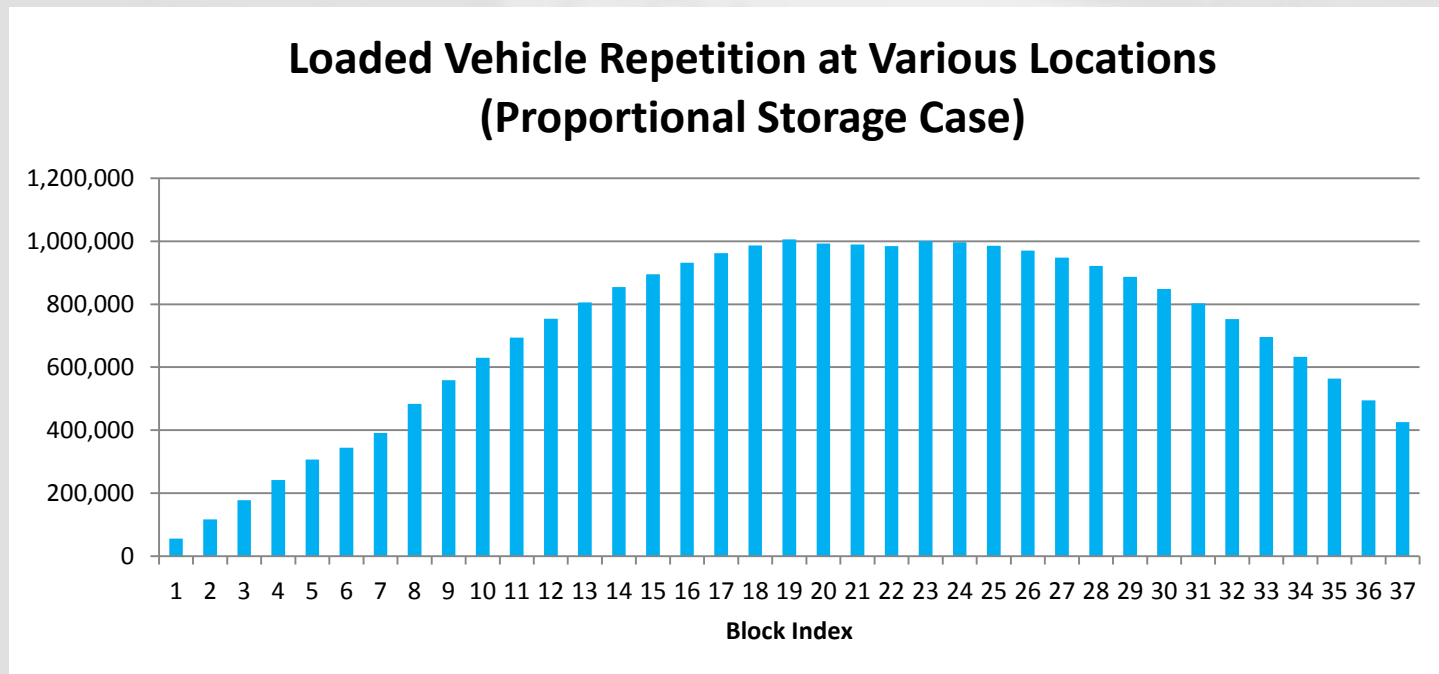
- Max Reps at middle of blocks
- 1M reps  $\sim$  55% of terminal throughput



# Vehicle / Wheel Repetition

## *Proportional Storage Case*

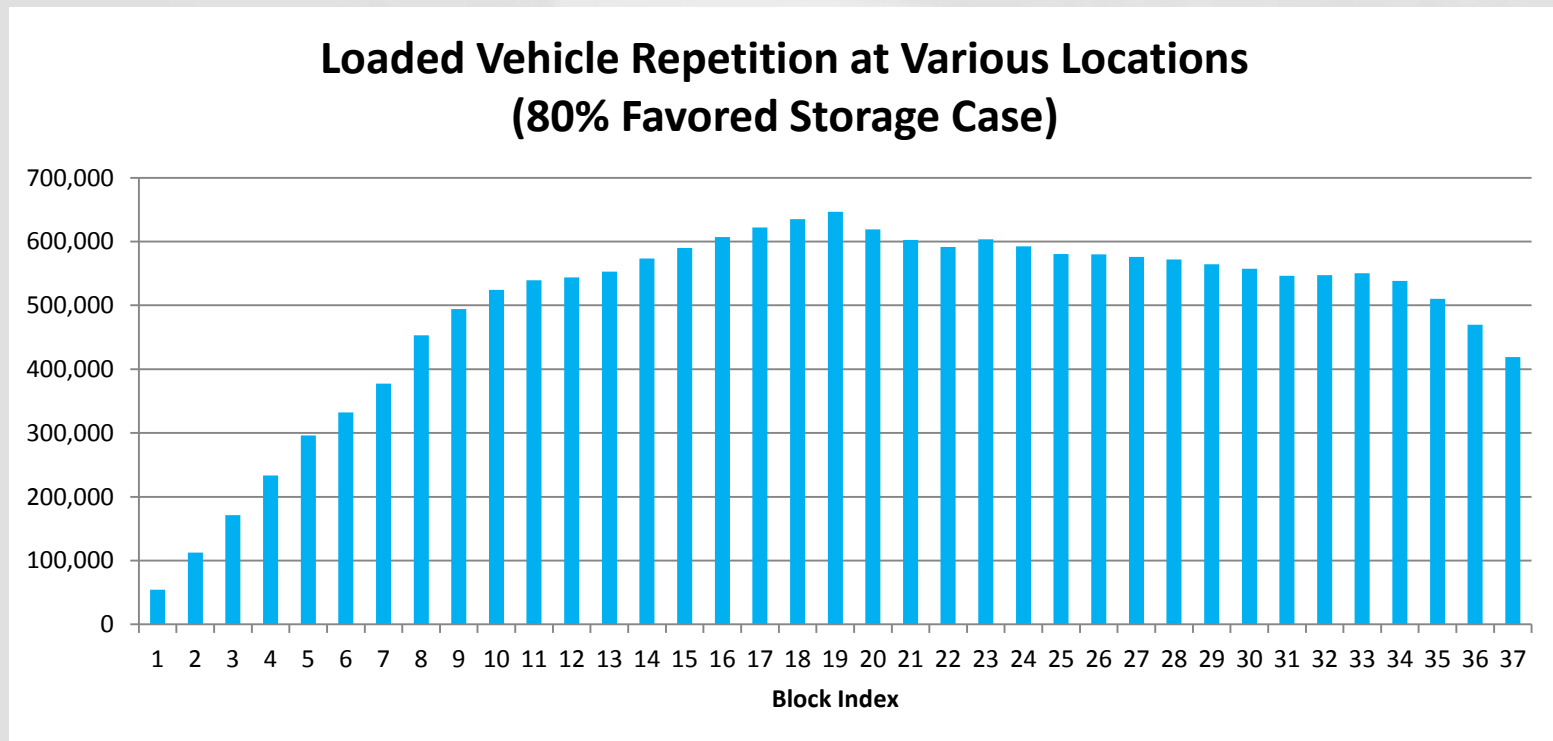
- Max Reps at middle of blocks
- 1M reps  $\sim$  55% of terminal throughput



# Vehicle / Wheel Repetition

## *Favored Storage Case*

- Max Reps flattened and reduced
- 0.65M reps  $\sim$  35% of terminal throughput



# Vehicle / Wheel Repetition

## *Summary of Result*

Allocation Assumptions	Equal Storage	Proportional Storage	Favored Storage					Worst Case
			40%	50%	60%	70%	80%	
Max Vehicle Repetition (Loaded)	998,746	1,005,520	973,410	891,698	809,986	728,275	646,563	<b>1,005,520</b>
Block Location When Max Repetition Takes Place	23	19	19	19	19	19	19	<b>19</b>
Percentage of Throughput	54%	55%	53%	49%	44%	40%	35%	<b>55%</b>



# Other Pavement Performance Factors

- Performance after Earthquake
  - PCC
    - Significant damage expected during DE
    - Catastrophic failure
    - Will take months to repair
    - Significant impact to operation to replace pavement
  - AC or Paver Block on CTB
    - Some damage during OLE
    - Can be repaired rapidly
      - Overlay AC on top
      - Adjust paver blocks

# Other Pavement Performance Factors

- Transponder Installation for AGV
  - App. 20 mm in diameter, 50 mm long (2 inches) glass body sealed with foam cushioning
  - Insert in holes 25 mm in diameter, 80 mm (3 inches) deep, sealed with glue
  - Leaving 0.5 inch gap between transponder and RCC pave for 3-inch AC
- 3-inch AC if rutted, damage on Transponder?



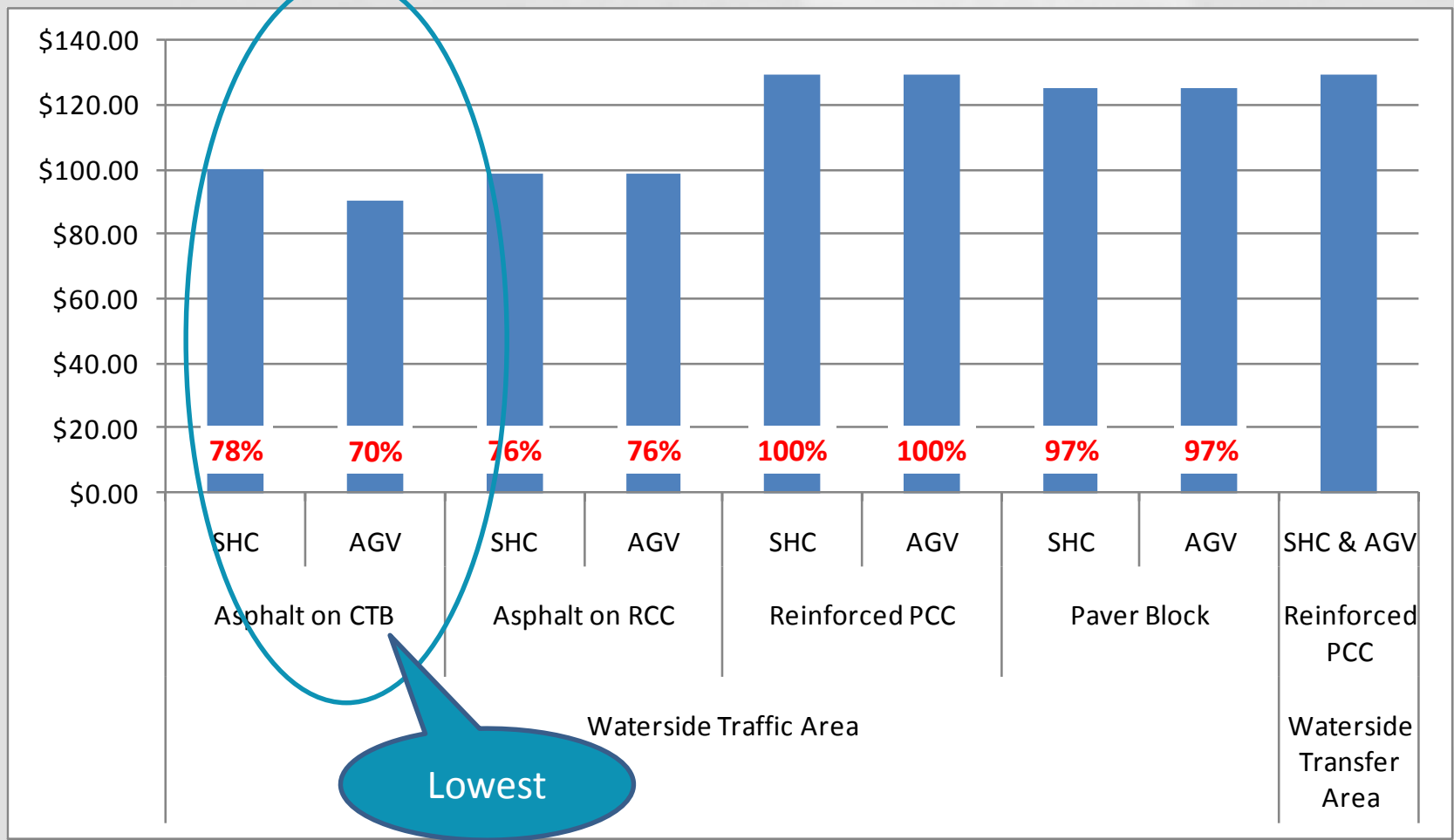
# Other Pavement Performance Factors

- Rescue of Automated Equipment
  - Typical rescue method for AGV
    - Reach stackers
    - Permanent damage to pavement
  - Alternative rescue method
    - By terminal trucks with “gooseneck”
    - Lighter wheel load



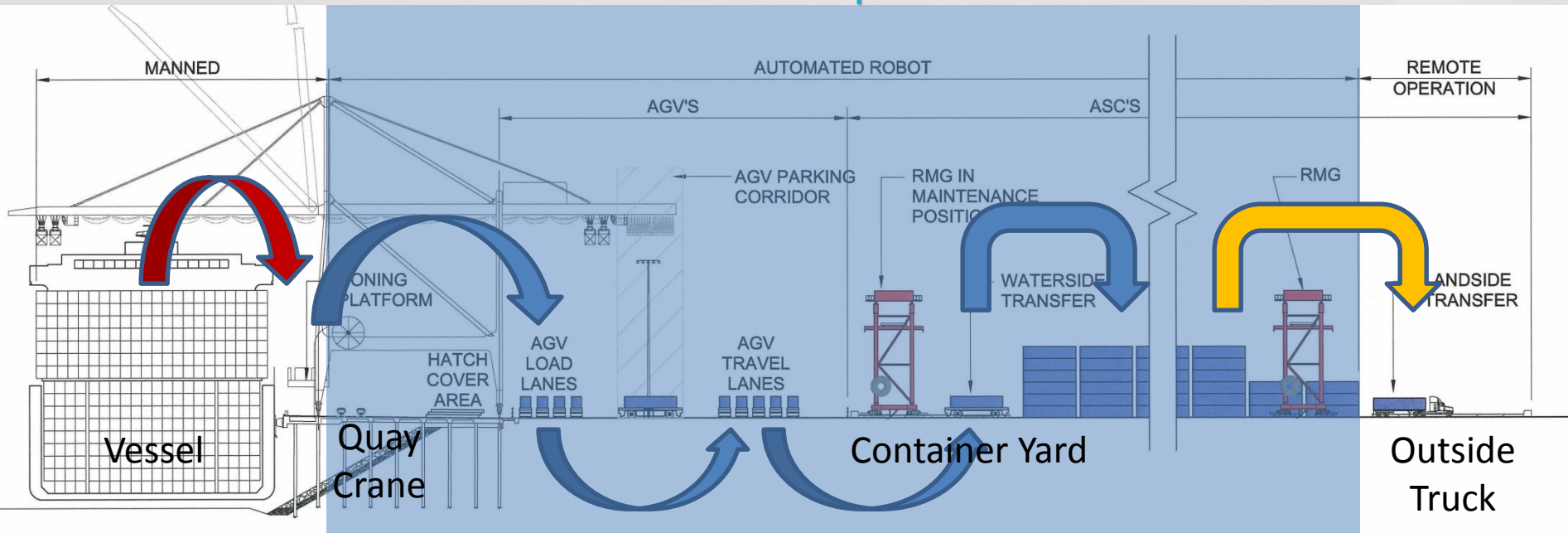
# Comparative Cost

- Life Cycle Cost Summary



# Automated Stacking Area

## Robotic Operation



Manned  
Main Trolley

Automated  
Secondary  
Trolley

Automated  
Horizontal  
Transport  
AGV's

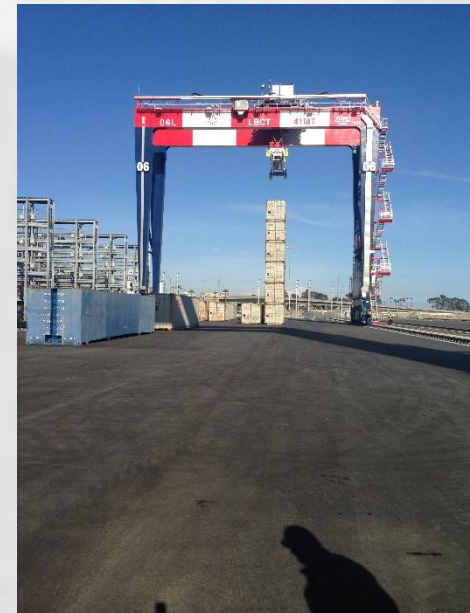
Automated  
Container  
Stacking,  
Retrieval,  
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Semi-  
Automated  
Delivery to  
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Truck



# Container yard

- End-loaded stacking/retrieval cranes
- Side-loaded stacking/retrieval with landside transfer cranes







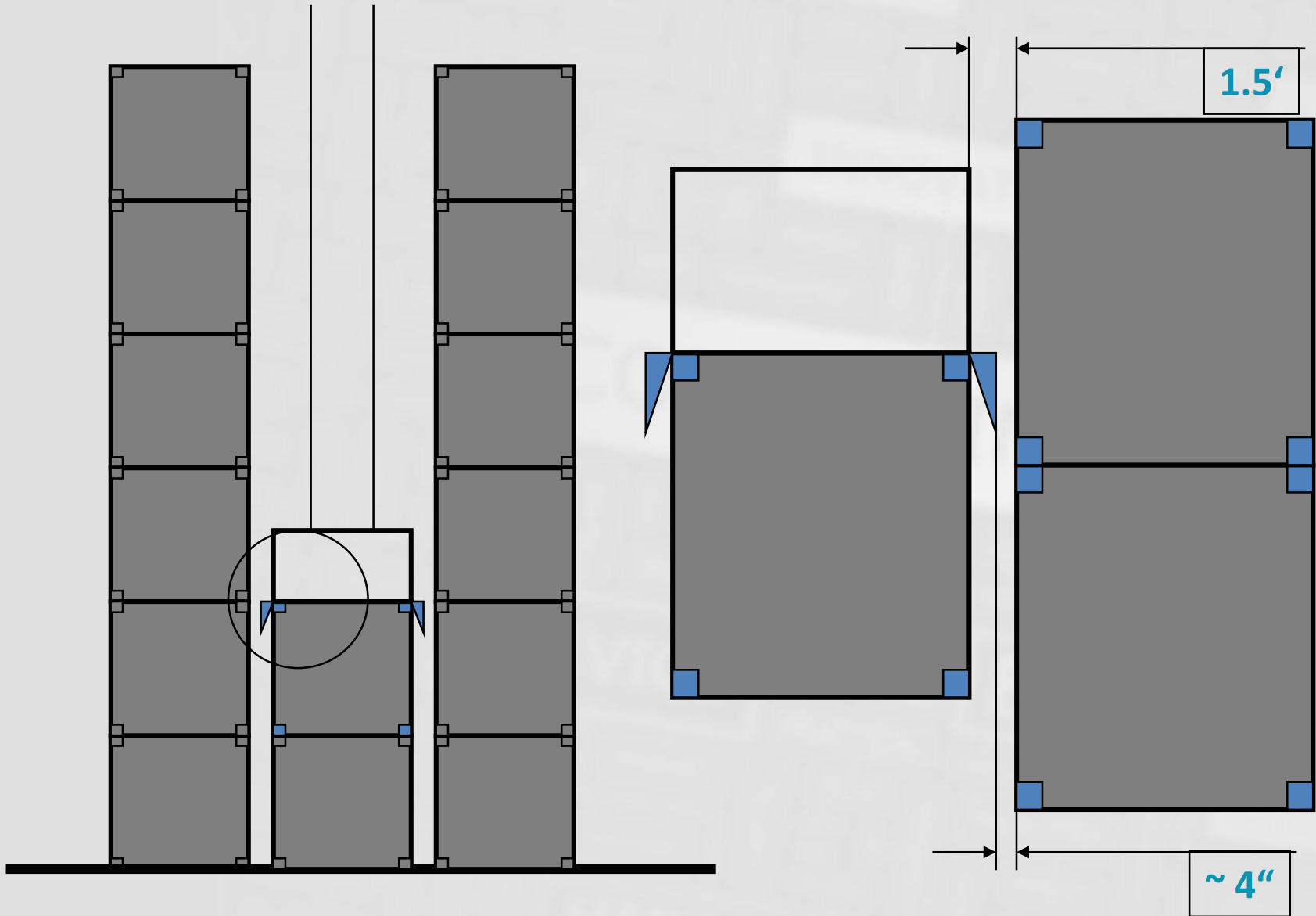
Why Low Tolerance?

4  
2

A close-up photograph of a heavily rusted metal structure, likely a ship's hull or a large industrial container. The metal is a mix of brown, orange, and grey, showing significant corrosion. A teal-colored semi-transparent band runs horizontally across the middle of the image. The background shows vertical corrugated metal panels on the left and a smoother orange-brown surface on the right.

Why Low Tolerance?

# Why Low Tolerance?





# Well Consolidated Landfill

- Critical to minimize total and differential settlements due to:
  - Dynamic loads created by crane operation
  - Stacked container storage
  - Impact loads from container stacks



# Drainage

- Stacking area flat and drainable
- Drainage and storm water treatment
  - Design slope that meets operational requirements
  - Comply with local regulation in treating storm water





# Other Utilities

- Fresh water supply
- Sanitary sewer
- Light poles (do we need any?)
- Antenna poles
- Camera poles
- Fencing
- X-ray inspection (VACIS)
- Fire protection
- Security systems

# Power System

- Redundancy
- 100% fault tolerance
- Reliable
- Location and size of substations, transformer
- Each crane in same stack energized from two independent sources



# Design Issues ASC Blocks

- RMG rails and beams
- Reefers
- Hazardous
- Grading and drainage

# Reefer Racks

- Clear understanding of operational requirements
- Consider all safety requirements
- Understand the access control and interfaces with crane system
- Comply with building requirements





A photograph of a port construction site. In the foreground, two parallel steel tracks run towards the center. To the left, there are stacks of green and blue shipping containers, with the word 'EVERGREEN' visible on some. A tall blue crane stands in the middle ground. The background shows more containers, a city skyline, and several tall light poles under a clear sky. A semi-transparent blue banner with the text 'ASC Runway' is overlaid across the middle of the image.

# ASC Runway





# Pre-fabricated Runway Beams

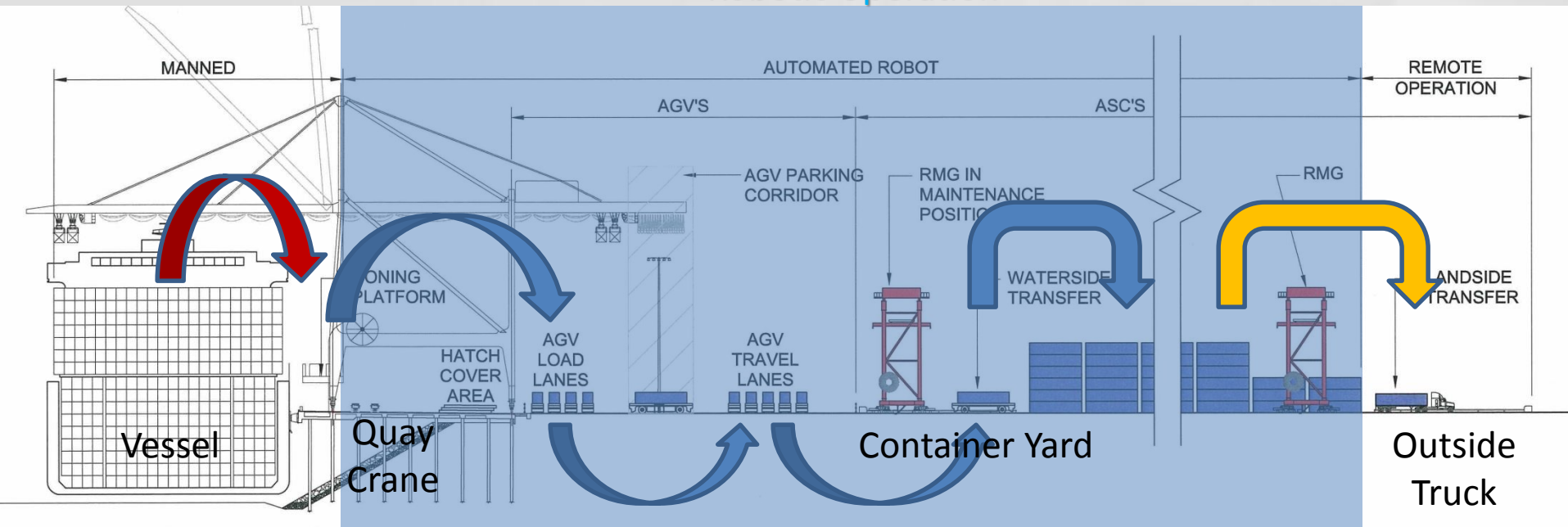
A large yellow automated guided vehicle (AGV) is shown from a low angle, moving along a set of steel rails. The rails are laid on a bed of grey gravel, with wooden sleepers visible. To the left of the tracks is a wide, flat, light blue paved area. In the background, there are stacks of red and blue shipping containers, a white industrial building with a smokestack emitting a plume of white smoke, and a tall lattice crane. Two workers in orange safety vests are visible in the distance on the right. The sky is clear and blue.

# ASC Runway



# Land Side Transfer Area

## Robotic Operation



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Semi-  
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Outside  
Truck

# Landside Transfer Area

- Understand the operational requirements
- Interface with gate systems
- Interface with ASC control/ safety systems
- Load repetition
- Durability of pavement



# Landside Transfer Area

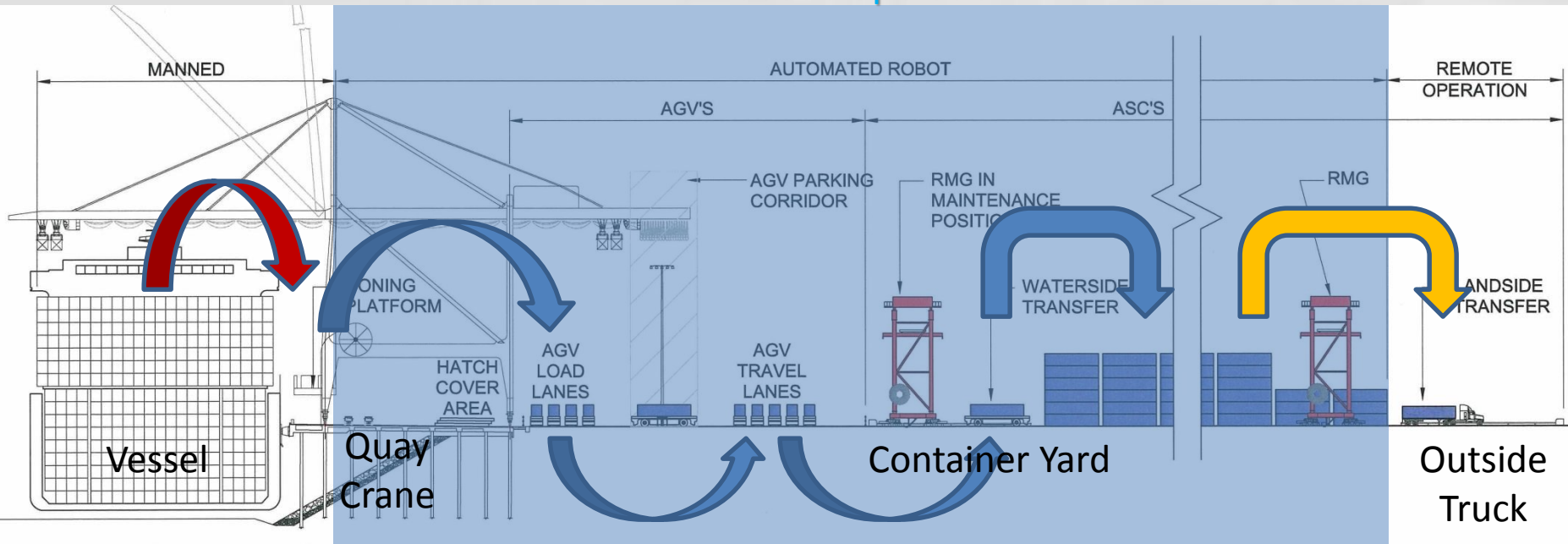
- Truck maneuvering to the transfer area
- Use island to locate electrical substations and communication hub building





# Intermodal Rail Area

## Robotic Operation



Manned  
Main Trolley

Automated  
Secondary  
Trolley

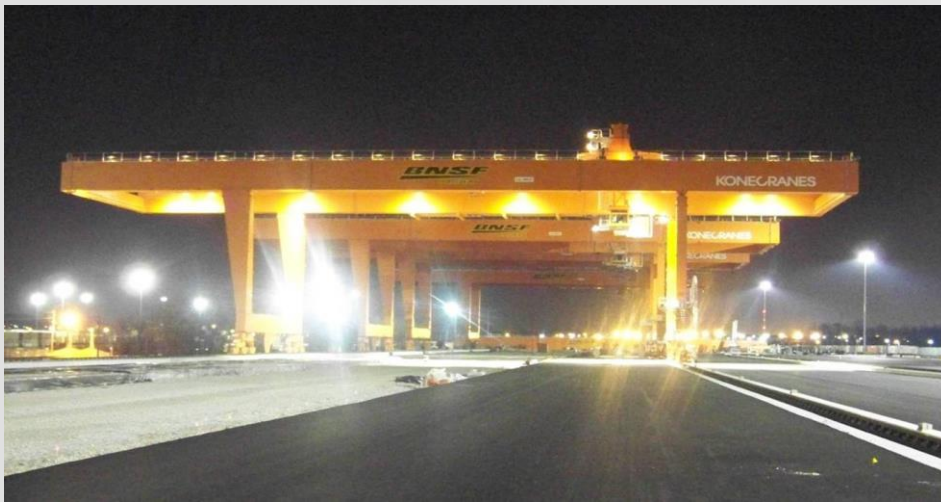
Automated  
Horizontal  
Transport  
AGV's

Automated  
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Automated  
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Truck

# IY Area

- On dock rail
- Designed for efficient rail loading operations
  - Semi-automated remotely operated rail loading cranes
  - Safety fence and gate locations and access control
  - The right crane rail







# Rail Operation



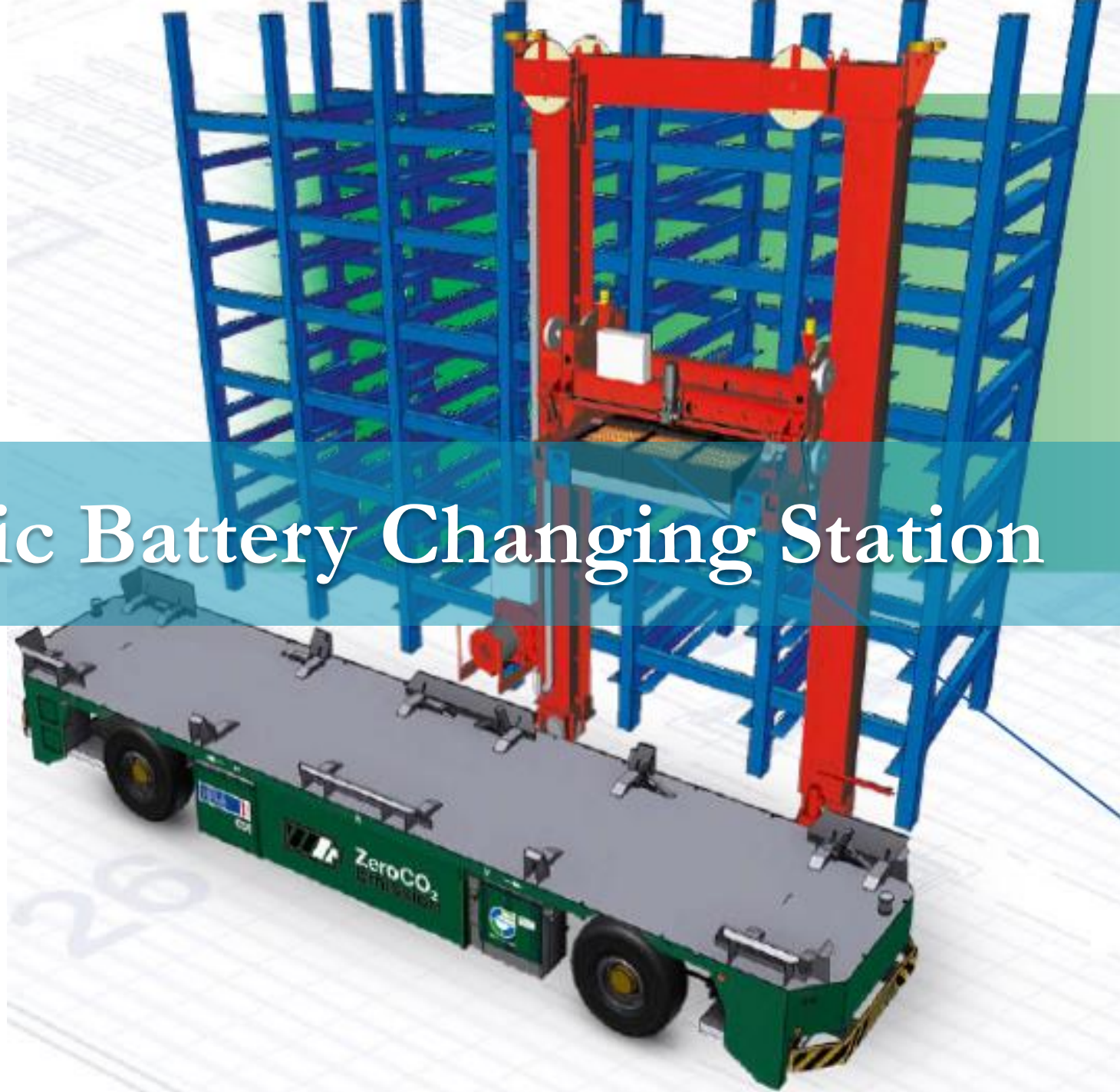


# Buildings



- Gates
  - Highly automated
  - RFID for truck identification
  - OCR
  - TWIC reader for security
  - Truck holding areas
- Administration/Operation/IT
  - House IT systems
  - Remote operator's room(s)
  - Other operation
- Maintenance
  - Provide sufficient storage for spare parts
  - Almost all electrical equipment
  - Almost all maintenance is performed at the equipment site, not in the workshop
  - Connected to IT systems
  - Location depends on
    - Mode of waterside transport
    - Mode of fueling (battery/diesel)
- Battery Exchange Building

# Robotic Battery Changing Station





# Example of Operations Control Room



- Orientation
- Windows
- Light
- Noise
- Table space

# Integration Management

- An automated terminal is a highly integrated system of components that must fit together perfectly
- The only standard is the container

**THIS IS WHERE PROJECTS TYPICALLY  
SUCCEED OR FAIL**



Thank You